## Learning Sentences and Assessments in Probabilistic Description Logics

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## Outline

## Introduction



- 3 Learning Description Logics
  - Learning CRALC
- 5 Preliminary Results
- 6 Conclusions



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• Representation of uncertainty in the semantic Web can be favoured by the use of learning techniques



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- Caveats in syntax and semantics in PDL have prevented them from spreading into several domains



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- It can be hard to elicit the probability component of a particular set of sentences



- Representation of uncertainty in the semantic Web can be favoured by the use of learning techniques
- Caveats in syntax and semantics in PDL have prevented them from spreading into several domains
- It can be hard to elicit the probability component of a particular set of sentences
- Focus in CRALC language



## **Previous Efforts**

Focus on Concept definitions

Using Noisy-OR classifiers



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## **Previous Efforts**

Focus on Concept definitions

Using Noisy-OR classifiers

Focus on Probabilistic inclusions  $C \equiv A \cup B \rightarrow P(C|A \cup B), P(C|A), P(C|B)$ 



## Combined approach $\rightarrow$ an algorithm for learning concept definitions and probabilistic inclusions at once



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Mostly based on inductive logic programming techniques with a probabilistic twist



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Mostly based on inductive logic programming techniques with a probabilistic twist

- A search for the best concept description is performed.
- A decision is made as to whether to consider the concept definition found or to insert a probabilistic inclusion based on this concept



Probabilistic Description Logic CR $\mathcal{ALC}$ 

## Probabilistic Description Logic CRALC

#### • CRALC is a probabilistic extension of the DL ALC.



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## Probabilistic Description Logic CRALC

- CRALC is a probabilistic extension of the DL ALC.
- The following constructors are available in *ALC*: conjunction (C □ D), disjunction C □ D, negation (¬C), existential restriction (∃r.C), and value restriction (∀r.C).



Probabilistic Description Logic  ${\tt CRALC}$ 

## Probabilistic Inclusions and their Semantics





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Probabilistic Description Logic CRALC

## Probabilistic Inclusions and their Semantics

• 
$$P(A|B) = \alpha$$
  
•  $\forall x \in \mathcal{D} : P(A(x)|B(x)) = \alpha$ 



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Probabilistic Description Logic CR $\mathcal{ALC}$ 

## Probabilistic Inclusions and their Semantics

- $P(A|B) = \alpha$
- $\forall x \in \mathcal{D} : P(A(x)|B(x)) = \alpha$
- P(Professor(Maria)|Researcher(Maria)) = 0.4



## Example

P(Animal) = 0.9,P(Rational) = 0.6,P(hasChild) = 0.3,Human  $\equiv$  Animal  $\sqcap$  Rational, Beast  $\equiv$  Animal  $\sqcap \neg$  Rational. Parent ≡ Human  $\sqcap \exists$ hasChild.Human. P(Kangaroo|Beast) = 0.4, $P(\text{Kangaroo}|\neg\text{Beast}) = 0.0,$ MaternityKangaroo  $\equiv$ Kangaroo  $\Box \exists$ hasChild.Kangaroo



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- Human □ ∃hasChild.Human.
- P(Kangaroo|Beast) = 0.4,
- $P(Kangaroo|\neg Beast) = 0.0,$
- $MaternityKangaroo\equiv$
- Kangaroo  $\sqcap \exists$ hasChild.Kangaroo





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## Example

P(Animal) = 0.9, P(Rational) = 0.6, P(hasChild) = 0.3,  $Human \equiv Animal \sqcap Rational,$   $Beast \equiv Animal \sqcap \neg Rational,$   $Parent \equiv$   $Human \sqcap \exists hasChild.Human,$   $P(Kangaroo| \exists Beast) = 0.4,$  $P(Kangaroo| \neg Beast) = 0.0,$ 

MaternityKangaroo  $\equiv$ 

Kangaroo ⊓ ∃hasChild.Kangaroo

Inference

$$P(Parent(0)|Human(0)) = 0.232$$





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#### Goal

Find a correct concept with respect to given examples. A sound concept definition for Target must cover all positive examples and none of the negative examples



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YINYANG



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- DL-FOIL



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- YINYANG
- DL-FOIL
- DL-Learner



## Learning Steps

#### **Refinement Operators**

#### Generalization and specialization $\rightarrow \theta$ -subsumption



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Score Function  $\mathcal{K} \cup \mathcal{C} \models \mathbf{e}$  (instance checking)



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Generalization and specialization  $\rightarrow \theta$ -subsumption

Score Function  $\mathcal{K} \cup \mathcal{C} \models \mathbf{e}$  (instance checking)

#### Search Algorithm

FOIL-based, genetic algorithms, horizontal expansion



## Assumption

Deterministic

 $Father \equiv Male \sqcap hasChild. \top$ 



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## Assumption

Deterministic Father  $\equiv$  Male  $\sqcap$  hasChild. $\top$ 

Probabilistic  $P(FlyingBird|Bird) = \alpha$ 



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Father  $\equiv$  Male  $\sqcap$  hasChild. $\top$ 

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#### Assumption

Negative and positive examples underlie the choice of either a concept definition or a probabilistic inclusion



## Proposal

 We expect to find concepts covering all positive examples which is not always possible → uncertainty



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## Proposal

- We expect to find concepts covering all positive examples which is not always possible → uncertainty
- When we are unable to find a concept definition that covers all positive examples we assume such hypothesis as candidates to be a probabilistic inclusion



#### **Refinement Operators**

Previous refinement operators



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#### **Refinement Operators**

Previous refinement operators

Probabilistic score function

$$\mathit{cover}(e,\mathcal{K},\mathit{C})=\mathit{P}(e|\mathcal{K},\mathit{C}).$$



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#### **Refinement Operators**

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#### Search

• We start by searching a deterministic concept



#### **Refinement Operators**

Previous refinement operators

#### Probabilistic score function

$$cover(e, \mathcal{K}, C) = P(e|\mathcal{K}, C).$$

#### Search

- We start by searching a deterministic concept
- If after a set of iterations the score of the best candidate is below a given threshold, a search for a probabilistic inclusion is started



## The Algorithm

**Require:** an initial knowledge base  $\mathcal{K} = \langle \mathcal{T}, \mathcal{A} \rangle$  and a training set E.

1: Search Tree with a node  $\{C=\top, h=0\}$ 

2: repeat

- 3: choose node  $N = \{C, h\}$  with highest probabilistic score in SearchTree
- 4: expand node to length h + 1:
- 5: add all nodes  $D \in (\text{refinementOperator}(C))$  with lenght =h+1
- 6: learn parameters for all nodes D
- 7:  $N = \{C, h+1\}$
- 8: expand alternative nodes according to horizontal expansion factor and h + 1[18]
- 9: until stopping criterion
- 10: N' = best node in SearchTree
- 11: if score(N') > threshold then
- 12: return deterministic concept  $C' \in N'$

13: else

- 14: call ProbabilisticInclusion(SearchTree)
- 15: end if

Algorithm 1: Algorithm for learning probabilistic terminologies.



## Probabilistic Inclusion Algorithm

Require: SearchTree previously computed

- 1: for each pair of candidates  $C_i, C_j$  in first k nodes of the SearchTree do
- 2: compute the conditional mutual information  $I(C_i, C_j|T)$
- 3: end for
- 4: build an undirected graph in which vertices are the k candidates
- 5: annotate the weight of an edge connecting  $C_i$  to  $C_j$  by the  $I(C_i, C_j|T)$
- 6: build a maximum weight spanning tree from this graph
- 7: add T as parent for each  $C_i$
- 8: learn probabilities for  $P(C_i | Parents(C_i))$
- 9: return the highest probabilistic inclusion  $P(T|C') = \alpha$

Algorithm 2: Algorithm for learning probabilistic inclusions.



## **Description Logic Learning Results**

#### Table: Description logic learning results

Problem	axioms, examples	DL-learner	Combined approach
		correct (length)	correct(length)
trains	252,10	100%(5)	100%(5)
arches	47,5	100%(9)	100%(10)
moral	31,43	100%(3)	100%(5)
poker(pair)	35,49	100%(8)	100%(8)
poker (straight)	45,55	100%(5)	100%(5)



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## A Real World Domain



#### Wikipedia

Wikipedia articles consist mostly of free text, but also contain various types of structured information in the form of Wiki markup



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Several Projects

DBPedia and YAGO



**Preliminary Results** 

## YAGO



 YAGO knows more than 2 million entities (like persons, organizations, cities, etc.)



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## YAGO



- YAGO knows more than 2 million entities (like persons, organizations, cities, etc.)
- It knows 20 million facts about these entities: actedIn ....



## YAGO



- YAGO knows more than 2 million entities (like persons, organizations, cities, etc.)
- It knows 20 million facts about these entities: actedIn ....
- Scientists and film directors domains



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## Scientists Dataset

2008 potential scientists have been considered

	P(wrotes) = 0.4
	P(hasAcademicAdvisor) = 0.80
	P(interestedIn) = 0.6
	P(diedOnYear) = 0.7
	P(hasWonPrize) = 0.4
	P(worksAt) = 0.85
	P(influences) = 0.6
Scientist $\equiv$	Person
	□(∃hasAcademicAdvisor.Person
	□ ∃wrotes.Text □ ∃worksAt.EducationalInstitution)
P(InfluentialScientist	Scientist ⊓ ∃influences.
	∃diedOnYear.Year) = 0.85
P(Musician	Person □ ∃hasAcademicAdvisor.∃wrote.Text) = 0.1
HonoredScientist $\equiv$	Scientist
	□ ∃hasWonPrize.Prize



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## Scientists II

## $\begin{array}{ll} P(Scientist(0) & |Person(0) \\ & & \sqcap(\exists wrote.Text(1) \\ & & \sqcap \exists hasAcademicAdvisor.Person(2)) = 0.5 \end{array}$



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## Scientists II

## $\begin{array}{ll} P(\text{Scientist}(0) & |\text{Person}(0) \\ & & & & \\ \sqcap(\exists wrote.\text{Text}(1) \\ & & & \\ \sqcap \exists hasAcademicAdvisor.\text{Person}(2)) = 0.5 \end{array}$

# $\begin{array}{ll} P(Scientist(0) & |Person(0) \\ & \sqcap(\exists wrote.Text(1) \sqcap \exists hasAcademicAdvisor. \\ & \exists influences.Person(3))) = 0.65 \end{array}$



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## Directors

5589 potential directors have been considered

 $Actor \equiv P(Director)$ 

 $P(\text{FomerActor} \ \text{HonoredDirector} \equiv \ \text{FamilyDirector} \equiv P(\text{InfluentialDirector})$ 

P(MostInfluentialDirector

P(isMarriedTo) = 0.1P(influences) = 0.35P(hasWonPrize) = 0.28P(hasChild) = 0.05P(diedOnYear) = 0.5P(directed) = 0.8P(actedIn) = 0.4Person 
VactedIn Film Person  $\sqcap$  ( $\exists$ directed.Film  $\sqcap$   $\exists$ influences.  $\exists actedIn.Film) = 0.75$ Director  $\sqcap \exists actedIn.Film) = 0.6$ Director □ ∃hasWonPrize.Prize Director  $\sqcap$  ( $\exists$ isMarriedTo.Director  $\sqcup \exists$ hasChild.Director) Director  $\square \exists$ hasWonPrize.Prize  $\square \exists$ influences.  $\exists isMarriedTo.Director) = 0.7$ Director □ ∃diedOnYear Year □ ∃influences.  $\exists$ hasWonPrize.Prize) = 0.8

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## **Directors II**

## $P(\text{Actor}(0)|\text{Person}(0) \sqcap \exists actedIn.Film(1) \sqcap \exists directed.Film(2)) = 0.4$

#### $P(\text{Director}(0)|\text{Person}(0) \sqcap \exists \text{actedIn}.\text{Film}(1) \sqcap \exists \text{directed}.\text{Film}(2)) = 0.55$



## **Directors II**

## $P(\text{Actor}(0)|\text{Person}(0) \sqcap \exists actedIn.Film(1) \sqcap \exists directed.Film(2)) = 0.4$

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$$\begin{array}{ll} P(Actor(0) & |Person(0) \\ & & \sqcap(\exists actedIn.Film(1) \sqcap \exists directed.Film(2) \\ & & \sqcap \exists influences.Person(3))) = 0.3 \end{array}$$



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• We have produced a combined scheme, where both the deterministic and probabilistic components receive due attention.



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- Initially, the search aims at finding deterministic concepts. If the score obtained is below a given threshold, a probabilistic inclusion search is conducted



- We have produced a combined scheme, where both the deterministic and probabilistic components receive due attention.
- Initially, the search aims at finding deterministic concepts. If the score obtained is below a given threshold, a probabilistic inclusion search is conducted
- Preliminary results have focused a real-world domain —YAGO ontology based on Wikipedia



## The End

Thank you



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