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Presentation Outline
 Linear Referencing Background Historical Uses Justification for using Linear Referencing for IED Analysis
 Implementation Network Representation Generating the Linearly Referenced Network Database
 Outputs Visualizations Network-based spatial statistics Measures of incident intensity on the network
 Ongoing/Future Research Linearly Referencing Human/Physical Terrain Characteristics Generate measures of Risk or Demand for Route Clearance Team (RCT) services for segments of the road network
 Additional Network-based spatial statistics Optimization of RCT services based on Linearly Referenced Demand FOR OFFICIAL USE ONLY











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OUTPUTS – LINEARLY REFERENCED IED DATABASE																		
	•	Peri	mit	s Sp	atial	Sun	nmar	y by l	Rout	e or S	Segm	lent						
Sum of	Count	Route 💌																
Year	2004	R01 44	R02	R03	3 R	208	05 R	06 RI	18 18	08 RI	09 F	10 R1	1 R1:	2 R13	R1	4	R15 (blank)	Grand Total
	2005	102		183	51	362	22	62	24	101	8	51	44	16	1	195	1055	2277
	2006	137		175	7	408	4	75	67	255	24	71	16	16	11	445	2500	4211
	2007	140		282	17	418	34	122	68	287	28	131	19	34	36	645	3345	5606
(blank)	2008	93		142	14	91	47	34	15	99		92	15	19	15	356	822	1991
Grand	Total	516		821	119	1487	116	315	192	802	68	355	116	87	70	1723	8290	15077
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- Ability to locate events (IEDs, terrain, etc.) through linear referencing
- Goal of optimizing RCT activities
- Initial formulation Maximal Covering Location Problem
 - Measure of priority for covering any section of the network is a function of:
 - Risk of IED, or demand for RCT services
 - Generated in Task 4
 - May be possible to add temporal component
 - · Model time patterns observed in the data • To meet scheduling needs of the RCTs
 - Future work must combine Blue, Red, and Green activities

S = the acceptable service distance (covering distance) $N_{ii} = [k \text{ in } K | \min(d_{ki}, d_{ki}) \le S]$ y_{ij} = the number of RCTs covering the arc from *i* to *j* x_k = the number of RCTs assigned to base location k a_{ij} = the measure of priority for covering the arc from *i* to *j* $\operatorname{Max} \sum_{(i,j)\in E} a_{ij} y_{ij}$ $\sum_{k \in K} x_k = P$ $\sum_{k \in N_{ij}} x_k \ge y_{ij} \quad \forall \ (i,j) \in E$ MASON FOR OFFICIAL USE ONLY

P = the number of RCTs available to patrol the network



FOR OFFICIAL USE ONLY ONGOING/FUTURE RESEARCH – ADDITIONAL NETWORK BASED SPATIAL STATISTICS
The Linear Nearest Neighbor method:
 Uses only the nearest neighbor distance (what about 2nd nearest, 3rd nearest etc.)
 Describes only if clustering occurs globally on the study area (the segment in our case)
 Cannot specify the locations and sizes of the clusters If we can identify which incidents are in which cluster we can identify which types of
incidents are clustering
• Next steps are to explore:
 Network Based K-functions
Multi-Distance Spatial Cluster Analysis
Summarizes spatial dependence over a range of distances
 Local K-function to identify clusters explicitly
• End
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